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Thermo-mechanical analysis of heat exchanger design for thermal energy storage systems

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9 Abstract

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Significant tensile stresses inside solid thermal energy storage media are induced due to incompatible thermal expansion characteristics. These stresses can cause damage to the often brittle storage material which is associated with a performance loss of thermal properties or the partial loss of long-term mechanical stability. In the present paper, a previously introduced analytical approach is extended to estimate the effects of the dominant physical and geometrical quantities on critical tensile stresses around tubular heat exchangers. Results are presented in terms of three composite dimensionless parameters representing the geometrical and material parameters of the system. Analytical sensitivities furthermore provide a direct quantification of how these sensitivities depend on selected system parameters, thus giving clues regarding the most promising optimisation handles. A representative case study was performed and can serve as a guide-line for making design decisions from a mechanical perspective as a complement to the typically performed thermodynamic design.

10 Keywords:

11 Sensible heat storage, Solid storage media, Thermo-mechanics, Heat exchanger design, Water-saturated

12 cement

13 1. Introduction

Driven by the purpose of saving fossil resources and reducing air pollution, alternative technologies are being developed to capture and use renewable sources of energy, such as solar, wind and hydro power, or geothermal heat. In this context, thermal energy storage (TES) is a technology that is primarily used for alleviating the mismatch between energy demand and supply at varying temperature conditions (Cabeza (2014)) and allows a better management of the intermittent renewable energy; cf., for example, Braun et al. (1981), Herrmann and Kearney (2002), Hesaraki et al. (2015).

Among the numerous technologies available, this article is concerned with sensible heat storage in solid media, which is extensively used in various heat storage applications (Herrmann et al., 2004; Laing et al., 2008; Bauer et al., 2010; Gil et al., 2010; Laing et al., 2012; Duffy et al., 2015; Jian et al., 2015b). This

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Nomenclature

 $\alpha_{1/2}$ Linear thermal expansion coefficient of the heat exchanger/the storage material.

 \mathcal{C} Fourth-order stiffness tensor.

 ϵ Small strain tensor.

 σ Cauchy stress tensor.

- $\nu_{1/2}$ Poisson's ratio of the heat exchanger/the storage material.
- $\sigma_{\phi\phi}^{1/2}$ Circumferential stress in the heat exchanger/the storage material.
- $\sigma_{rr}^{1/2}$ Radial stress in the heat exchanger/the storage material.
- φ Airy stress function.
- ϑ Temperature difference with respect to T_0 .
- A_i, C_i Integration constants.
- $E_{1/2}$ Young's modulus of the heat exchanger/the storage material.
- $p_{0/2}$ Pressure applied on the inner/outer boundary.
- $r_{0/1}$ Inner/outer radius of the tube.
- S Tube pitch $(S = 2r_2)$.
- T_0 Homogeneous reference temperature.
- $T_{\rm u}$ Ultimate storage temperature.

3 The continuing development of TES systems is accompanied by specific requirements for heat exchang-

4 ers. Not only does the heat exchanger need to be designed to achieve a high heat transfer efficiency (Zheng

et al., 2015), but also the thermo-mechanical and thermo-hydraulic performance of the heat exchanger and
the surrounding storage media must be improved to maintain functional reliability during the operational
life.

As there are numerous design aspects implied in the multi-disciplinary design of a heat exchanger for 8 solid sensible TES, presenting a comprehensive optimum may not be the most efficient and economical 9 procedure (Bao et al., 2013), and is not a uniquely posed problem. Accordingly, it is more reasonable 10 to concentrate on those factors that have been identified as the most dominant in a given specific kind of 11 TES system. Most existing studies focus on improving heat transfer performance along with overall cost 12 reduction. Although, the analyses of mechanical fields for TES materials were presented in literature (cf., 13 for example Su et al. (2005); Zhang and Zhao (2011); Yuan et al. (2012)), to the authors' knowledge, there 14 are few studies taking into account thermo-mechanical effects in the solid TES with heat exchangers, such 15 as critical stresses inside solid sensible TES during thermal cycling as well as quantifying the dependence of 16

¹⁷ these stresses on key parameters of the heat exchanger and the storage material and using that information

mature technology is cost-effective and can be qualified for most domestic and commercial applications
 while being environmentally benign.

¹ for design optimisation.

In this paper, we focus on estimating peak tensile stresses around tubular heat exchangers embedded in a 2 solid heat storage medium as an indicator for the thermo-mechanical integrity of the heat store. The specific 3 motivation for this problem comes from the observation of significant tensile stress within the storage ma-4 terial which is typically an affordable building material with a relatively low tensile strength (Skinner et al., 5 2014; Miao et al., 2016). Thus, such thermally induced stresses might quite possibly exceed the material's 6 strength limits for an inappropriate combination of geometry and material. The purpose of the present study 7 is twofold: i) to investigate the effects of geometrical/physical parameters of the heat exchanger on the 8 thermo-mechanical performance of the heat store unit in detail by using a previously developed analytical 9 approach; ii) to show how this analytical approach can be modified and used to select a heat exchanger 10 which is optimal from a mechanical perspective and does not stand in contrast to thermodynamic require-11 ments that are critical for the system's operation as a heat store. 12

Generally, a designated TES system is characterized by the geometric layout of its heat exchanger as well as the selected storage material which must satisfy the thermal performance requirements as well as provide long-term reliability. Mechanically, the incompatibility of the heat exchanger with the storage material in terms of material properties dominates the stresses induced by thermo-mechanical loads.



Figure 1: Schematic and details of standard tubular heat exchanger's geometrical layout.

The heat exchanger layout investigated here is based on Laing et al. (2006) and illustrated in Fig. 1a. According to the analytical solution presented in Miao et al. (2016), three quantities were considered as the main geometric design parameters in the analysis: the outer and inner diameters of the heat exchanger, and the tube pitch which is defined as the centre-to-centre distance between two adjacent cylindrical heat exchangers, see Fig. 1b. The above configuration aside, our approach applies to other configurations composed of piping bundles embedded within a solid storage material as well (for example Agyenim et al. (2010); Raju and Kumar (2012); Wu et al. (2014); Jian et al. (2015a)).

This paper is organised as follows. In Section 2, the analytical solution used in the analysis is briefly reviewed. Dimensionless geometrical/physical quantities are derived to reduce the number of free parameters and to simplify the illustration of the analysis. In Section 3, result are presented for the optimal layout of a specific system based on the identification of dominant thermo-mechanical aspects in extensive sensitivity

² analyses (Appendix B). The main conclusions of this paper are stated in Section 4.

3 2. Theoretical modelling

Heat transport models of the heat store were validated by distributed thermo-couple measurements [data not shown]. The stress fields within the cast cement block around the heat exchangers, however, cannot be readily measured and only indirect experimental evidence on their effects is available (Skinner et al., 2014).
This motivated us to use theoretical modelling as the apparently most feasible way for their quantification.
An extensively validated and simple linear thermo-elastic theory was employed and material parameters measured in the laboratory (Miao et al., 2016) were used.

To keep the approach simple and broadly applicable, it is based on a well-established engineering theory. The model describes a cylindrical region comprising the heat exchanger and the surrounding storage material and allows for an internal pressure as well as an external pressure acting on the cylinder walls.

¹³ The following assumptions were made to arrive at an analytical solution:

(i) All materials are assumed to behave linearly elastic and to be isotropic.

- 15 (ii) Body forces are not considered.
- 16 (iii) Axisymmetry of geometry and loading is assumed.

17 (iv) Radial displacement and radial stress are continuous at the interface.

Assumption (iv) carries the implicit assumption that $\alpha_1 \ge \alpha_2$, which is fulfilled in most practical cases. The basic constitutive equation with respect to stresses, strains and temperature changes is written based on the thermo-elastic relation

$$\boldsymbol{\sigma} = \boldsymbol{\mathcal{C}} : (\boldsymbol{\epsilon} - \alpha \vartheta \mathbf{I}) \tag{1}$$

Introducing a scalar valued stress function φ (Kreißig and Benedix (2013)), the biharmonic equation

$$\Delta\Delta\varphi = 0 \tag{2}$$

can be shown to hold. Due to axisymmetry, Eq. (2) can be expressed as an ordinary differential equation

$$\frac{\mathrm{d}}{\mathrm{d}r} \left\{ r \frac{\mathrm{d}}{\mathrm{d}r} \left[\frac{1}{r} \frac{\mathrm{d}}{\mathrm{d}r} \left(r \frac{\mathrm{d}\varphi}{\mathrm{d}r} \right) \right] \right\} = 0 \tag{3}$$

As outlined in Miao et al. (2016), a solution of Eq. (3) yields the following expressions for the stresses

$$\sigma_{rr}^i = \frac{A_i}{r^2} + 2C_i \tag{4}$$

$$\sigma^i_{\phi\phi} = -\frac{A_i}{r^2} + 2C_i \tag{5}$$

$$\sigma_{zz}^i = 4\nu_i C_i - E_i \alpha_i \vartheta_i \tag{6}$$

² The integration constants A_i , C_i can be determined by the continuity and boundary conditions and are

³ listed in Appendix A. For further details on the derivation as well as a comparison to numerical modelling

4 results, see Miao et al. (2016).

5 2.1. Dimensionless peak tensile stress

As outlined in Miao et al. (2016), the peak tensile stress typically occurs within the storage material in the circumferential direction at the interface:

$$\sigma_{\phi\phi}^2\big|_{r_1} = -\frac{A_2}{r_1^2} + 2C_2 \tag{7}$$

6 As the peak tensile stress is the most critical stress for commonly used brittle storage media such as cemen-

⁷ titious or ceramic materials, it will also be referred to as critical stress. For ease of notation, in the sequel ⁸ we will simply write $\sigma_{\phi\phi}$ when referring to this quantity. To simplify the analysis, all variables influencing ⁹ the critical tensile stress $\sigma_{\phi\phi}$ will be condensed into dimensionless quantities.

Suppose that negligible pressures are imposed on the boundaries, i.e., $p_0 = 0$ and $p_2 = 0$, and $T_u = const.$, i.e., the heat store is fully charged and at maximum homogeneous temperature which was confirmed to be the mechanically most critical practically occurring state by full transient heat transport simulations (Miao et al., 2016). Then, A_2 can be rewritten as

$$A_{2} = \frac{R_{0}E_{1}E_{2}r_{0}^{2}r_{1}^{2}r_{2}^{2}\left(\alpha_{2} - \alpha_{1}\right)\vartheta}{E_{1}r_{0}^{2}R_{0}\left[r_{2}^{2} + r_{1}^{2} + \nu_{2}\left(r_{2}^{2} - r_{1}^{2}\right)\right] - E_{2}r_{2}^{2}\left[r_{0}^{2} + r_{1}^{2} + \nu_{1}\left(r_{0}^{2} - r_{1}^{2}\right)\right]}$$
(8)

By introducing the dimensionless quantities

$$(r_0^*, r_1^*) = \frac{1}{r_2} (r_0, r_1), \ R_0^* = \frac{1 - \frac{r_1^2}{r_0^2}}{r_1^{*2} - 1},$$
(9)

$$E^* = \frac{E_1}{E_2}, \ \vartheta^* = (\alpha_2 - \alpha_1)\,\vartheta \tag{10}$$

$$\nu_1^* = \frac{1+\nu_1}{1+\nu_2}, \ \nu_2^* = \frac{1-\nu_1}{1-\nu_2}, \ M^* = \frac{\nu_2^*}{E^*},$$
(11)

the critical tensile stress normalised by the Young's modulus of the storage material can be written as:

$$\frac{\sigma_{\phi\phi}}{E_2} = -\frac{E^*\vartheta^*R_0^*\left(r_0^{*2} + r_0^{*2}r_1^{*2}\right)}{r_0^{*2}\left(1 + \nu_2\right)\left(E^*R_0^* - \nu_1^*\right) + r_1^{*2}\left(1 - \nu_2\right)\left(E^*R_0^*r_0^{*2} - \nu_2^*\right)}$$
(12)

¹⁰ The dimensionless parameter R_0^* includes geometric sizes characteristic of the analytical solution, such as ¹¹ the inner and outer pipe radii as well as the tube pitch $S = 2r_2$. M^* indicates the stiffness of the storage ¹² material in comparison to that of the heat exchanger. The higher M^* is, the stiffer the storage material gets ¹³ relatively. θ^* represents the difference in thermal strain between both materials at maximum ΔT .

The three quantities R_0^* , M^* and θ^* contain all ten parameters influencing the solution. In the following, the solution is used to obtain an optimum tube pitch, perform sensitivity analyses as well as a case study on how to select a suitable heat exchanger from a mechanical perspective.

17 3. Results

18 3.1. Sensitivity-based optimisation criterion

The dependence of the peak stress on multiple parameters provides flexibility regarding possible tech nical solutions satisfying specific design requirements of the heat store. Sensitivity analyses (see Appendix
 B) can serve as a guide-line for the design of the tube-type thermal storage in this respect.

- ³ As seen in Appendix B, increasing the tube pitch can lower the peak stress at the material interface up
- 4 to a threshold value of S, beyond which a further increase of S has no effect (Fig. **B.5c**). Following that,
- ⁵ Fig. 2 illustrates the peak tensile stress as it varies with the tube pitch.



Figure 2: Critical tensile stress $\sigma_{\phi\phi}$ varying with the tube pitch S.

After a sharp decline, the stress achieves asymptotically a constant value consistent with the observations in Appendix B. From an economic point of view, it is not necessary to extend the tube pitch any further as it does not lead to lower peak stresses. In combination with the observation that a fast heat input

⁹ into the heat store and an equally fast heat extraction from it, i.e., a high thermal power, require a sufficiently

¹⁰ tight packing of heat exchanger tubes or bundles, a certain optimum balance can be postulated: There is a

maximum spacing allowed from a thermal perspective and a minimum spacing required from a mechanical

perspective. Both measures can be combined into an objective function for a comprehensive optimisation.
 Here, the focus is exclusively on the mechanical contribution.

To define an optimal value, the lowest achievable peak stress $\sigma_{\rm mp}$ is here defined based on a threshold criterion as that stress where $|\mathcal{D}_S| \leq \varepsilon$ (see Fig. 2). Simultaneously, this defines the optimal tube pitch $S_{\rm mp}$ as that value of S that minimises the peak stress. $S_{\rm mp}$ is considered as a design parameter and an optimisation criterion. In this article, $\varepsilon = 1\%$ has been used.

18 3.2. Optimal tube-pitch in a novel heat store

All sensitivities investigated above change monotonically, except for those with respect to the inner and outer radii of the heat exchanger, which show a more complex variation, see Fig. B.5a and Fig. B.5b. To further study the effects of the radii on the peak stress and the tube pitch, a case study with prescribed geometrical sizes of the heat exchanger used in the present project (Miao et al., 2016) is conducted. Since

the heat exchanger material has been selected to be an aluminium-polyethylene composite, M^* can be considered fixed and so can θ^* for a given maximum storage temperature of 90 °C.

Fig. 3a illustrates the minimum peak tensile stress values achievable (σ_{mp}) with the given heat exchanger for the available pipe geometries according to the $|\mathcal{D}_S| \leq 1\%$ criterion. Corresponding to these stress

values, Fig. 3b plots the optimised tube pitch values at which the lowest critical stress values are achieved.

A comparison of both figures indicates the complex interactions between the peak stress, the tube pitch and

² the dimensions of the heat exchanger. The appropriate dimension which leads to the minimal peak stress

³ does not coincide with the minimal tube pitch, see Fig. 3a and Fig. 3b.

Considering the results, a good compromise may be to choose the 25 × 2.5 pipe, as it yields the lowest
 stress value of all pipes at a tube spacing of 75 mm, which—based on numerical studies not shown here—
 also provides the required thermal performance characteristics.



Figure 3: The peak stress and the tube pitch based on different dimensions of the heat exchanger made from an aluminium-polyethylene composite.

7 4. Conclusions

In this paper, a new analytical approach for aiding design choices in solid thermal energy storage with 8 tubular heat exchangers was proposed based on thermo-mechanical arguments. It captured the dominant fac-9 tors that affect the mechanical integrity of the heat store, and allowed the identification of optimal properties 10 in the sense of minimal induced stresses while maintaining thermal performance requirements. Sensitivity 11 analyses indicated the flexibility of selecting the appropriate heat exchanger for satisfying the design re-12 quirements mechanically or thermally. Additionally, analytical sensitivities directly yield their dependence 13 on all relevant parameters, which is a significant benefit of the analytical over a numerical approach. By 14 studying a currently developed system it was shown how a specific design choice regarding the optimal tube 15 pitch can be made. 1

2 Acknowledgements

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4 ("Analysis, modelling and assessment of an intelligent and environmentally neutral geothermal long-term

heat storage system", project acronym IGLU) and is gratefully acknowledged. 5

Appendix A. Integration constants 6

The integration constants required for Eqs. (4)-(6) are given by

$$A_{1} = \frac{E_{2} (1 - \nu_{1}) r_{0}^{2} r_{1}^{2} r_{2}^{2} p_{0} + E_{1} r_{0}^{2} \left[-r_{1}^{2} r_{2}^{2} p_{2} - R_{1} \left(r_{1}^{2} + r_{2}^{2} \right) \right] + E_{1} \nu_{2} r_{0}^{2} \left[r_{1}^{2} r_{2}^{2} p_{2} + R_{1} \left(r_{1}^{2} - r_{2}^{2} \right) \right]}{E_{1} r_{0}^{2} R_{0} \left[r_{2}^{2} + r_{1}^{2} + \nu_{2} \left(r_{2}^{2} - r_{1}^{2} \right) \right] - E_{2} r_{2}^{2} \left[r_{0}^{2} + r_{1}^{2} + \nu_{1} \left(r_{0}^{2} - r_{1}^{2} \right) \right]}$$

$$+\frac{E_1 E_2 r_0^2 r_1 r_2 \left[\alpha_2 \left(\psi_2(r)\right)_{r_1} - r_1 r_0\right) - \alpha_1 \left(\psi_1(r)\right)_{r_1} - r_1 r_0\right)\right]}{E_1 r_0^2 R_0 \left[r_2^2 + r_1^2 + \nu_2 \left(r_2^2 - r_1^2\right)\right] - E_2 r_2^2 \left[r_0^2 + r_1^2 + \nu_1 \left(r_0^2 - r_1^2\right)\right]}$$
(A.1)

$$A_{2} = R_{0}A_{1} + R_{1}$$

$$C_{1} = -\frac{1}{2}\left(p_{0} + \frac{A_{1}}{r_{0}^{2}}\right)$$

$$C_{2} = -\frac{1}{2}\left(p_{2} + \frac{A_{2}}{r_{2}^{2}}\right)$$
(A.2)
(A.3)
(A.4)

$$C_{2} = -\frac{1}{2} \left(p_{2} + \frac{1}{r_{2}^{2}} \right)$$
where $R_{0} = \frac{r_{2}^{2} \left(r_{0}^{2} - r_{1}^{2} \right)}{r_{0}^{2} \left(r_{1}^{2} - r_{2}^{2} \right)}$ and $R_{1} = -\frac{r_{1}^{2} r_{2}^{2} \left(p_{0} + p_{2} \right)}{r_{1}^{2} - r_{2}^{2}}$.

Appendix B. Sensitivity analyses

Appendix B. Sensitivity analyses 8

To determine the dominant physical parameters affecting the peak stress, sensitivity analyses were per-9 formed. To maintain physical intuition and facilitate interpretation, the dimensions of the problem are 10 maintained. The values and trends of the sensitivities will strongly depend on the reference state, i.e., the 11 point in the parameter space at which the derivatives will be taken. In order to maintain a specific link to 1 an ongoing project and to practically relevant parameter values, the baseline system parameters were set to 2 values employed in the IGLU project, compare Tab. B.1 and Fig. 3, and the maximum storage temperature 3 of 90 °C was used aligned with domestic requirements. For a more detailed description of the prototype, 4 the interested reader is referred to Miao et al. (2016). 5

To simplify the following expressions, we define

$$G(E_{1}, E_{2}, \alpha_{1}, \alpha_{2}, r_{0}, r_{1}, r_{2}) = E_{1}E_{2}R_{0}r_{0}^{2} \left(r_{1}^{2} + r_{2}^{2}\right) \left(\alpha_{2} - \alpha_{1}\right)\vartheta$$

$$F(E_{1}, E_{2}, \nu_{1}, \nu_{2}, r_{0}, r_{1}, r_{2}) = E_{1}R_{0}r_{0}^{2} \left[r_{2}^{2} + r_{1}^{2} + \nu_{2}\left(r_{2}^{2} - r_{1}^{2}\right)\right] - E_{2}r_{2}^{2} \left[r_{0}^{2} + r_{1}^{2} + \nu_{1}\left(r_{0}^{2} - r_{1}^{2}\right)\right]$$
(B.1)
(B.2)

The first-order partial derivatives of the circumferential tensile stress in the storage material at the interface $\sigma_{\phi\phi}$ with respect to the independent material parameters $(E_1, E_2, \nu_1, \nu_2, \alpha_1, \alpha_2)$ and the tube pitch $(\bar{S} = 2r_2)$ as well as the tube dimensions (r_0, r_1) can be found as

$$\mathcal{D}_{E_1} = \left. \frac{\partial \sigma_{\phi\phi}}{\partial E_1} \right|_{r_1} = -\frac{E_2 R_0 r_0^2 \left(r_1^2 + r_2^2 \right) \left(\alpha_2 - \alpha_1 \right) \vartheta F - G R_0 r_0^2 \left[r_2^2 + r_1^2 + \nu_2 \left(r_2^2 - r_1^2 \right) \right]}{F^2} \tag{B.3}$$

$$\mathcal{D}_{E_2} = \left. \frac{\partial \sigma_{\phi\phi}}{\partial E_2} \right|_{r_1} = -\frac{E_1 R_0 r_0^2 \left(r_1^2 + r_2^2 \right) \left(\alpha_2 - \alpha_1 \right) \vartheta F + G r_2^2 \left[r_0^2 + r_1^2 + \nu_1 \left(r_0^2 - r_1^2 \right) \right]}{F^2} \tag{B.4}$$

$$\mathcal{D}_{\nu_1} = \left. \frac{\partial \sigma_{\phi\phi}}{\partial \nu_1} \right|_{r_1} = \frac{GE_2 r_2^2 \left(r_1^2 - r_0^2 \right)}{F^2} \tag{B.5}$$

$$\begin{aligned} \mathcal{D}_{\nu_{2}} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial \nu_{2}} \right|_{r_{1}} = \frac{GE_{1}R_{0}r_{0}^{2}\left(r_{2}^{2} - r_{1}^{2}\right)}{F^{2}} & (B.6) \\ \mathcal{D}_{\alpha_{1}} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial \alpha_{1}} \right|_{r_{1}} = \frac{E_{1}E_{2}R_{0}r_{0}^{2}\left(r_{1}^{2} + r_{2}^{2}\right)\vartheta}{F} & (B.7) \\ \mathcal{D}_{\alpha_{2}} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial \alpha_{2}} \right|_{r_{1}} = -\frac{E_{1}E_{2}R_{0}r_{0}^{2}\left(r_{1}^{2} + r_{2}^{2}\right)\vartheta}{F} & (B.8) \\ \mathcal{D}_{r_{0}} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial r_{0}} \right|_{r_{1}} = -\frac{2GF - G\left\{E_{1}R_{0}2r_{0}^{2}\left[r_{2}^{2} + r_{1}^{2} + \nu_{2}\left(r_{2}^{2} - r_{1}^{2}\right)\right] - E_{2}r_{2}^{2}2r_{0}^{2}\left(1 + \nu_{1}\right)\right\}}{r_{0}F^{2}} & (B.9) \\ \mathcal{D}_{r_{1}} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial r_{1}} \right|_{r_{1}} = -\frac{E_{1}E_{2}R_{0}r_{0}^{2}2r_{1}\left(\alpha_{2} - \alpha_{1}\right)\vartheta F - G\left[E_{1}R_{0}r_{0}^{2}2r_{1}\left(1 - \nu_{2}\right) - E_{2}r_{2}^{2}2r_{1}\left(1 - \nu_{1}\right)\right]}{F^{2}} & (B.10) \\ \mathcal{D}_{S} &= \left. \frac{\partial \sigma_{\phi\phi}}{\partial S} \right|_{r_{1}} = -\frac{E_{1}E_{2}R_{0}r_{0}^{2}S\left(\alpha_{2} - \alpha_{1}\right)\vartheta F - G\left\{E_{1}R_{0}r_{0}^{2}S\left(1 + \nu_{2}\right) - E_{2}S\left[r_{0}^{2} + r_{1}^{2} + \nu_{1}\left(r_{0}^{2} - r_{1}^{2}\right)\right]\right\}}{F^{2}} & (B.11) \end{aligned}$$

⁶ These sensitivities represent the gradient of $\sigma_{\phi\phi}$ in the cement at the interface with respect to the speci-⁷ fied parameters. Note, that only one parameter is changed at a time, all other parameters remaining fixed.

⁸ Eq. (B.7) and Eq. (B.8) imply that the relation between the peak stress and the thermal expansion ⁹ coefficient is linear, i.e. the sensitivity \mathcal{D} is independent of the parameter itself. \mathcal{D}_{α_1} is positive while \mathcal{D}_{α_2} ¹⁰ is negative. In the reference state, $\mathcal{D}_{\alpha_1} = 125$ GPa K and $\mathcal{D}_{\alpha_2} = -125$ GPa K. This is reminiscent of the fact ¹¹ that due to the inherent assumption of $\alpha_1 \ge \alpha_2$ a decrease in stress can be brought about by a decrease of ¹² $\alpha_1 - \alpha_2$, which can be achieved either by increasing α_2 or by decreasing α_1 .

As shown in Fig. B.4a and Fig. B.4b, the sensitivity to changes in the Young's modulus of the storage material is about three orders of magnitude higher than to that of the heat exchanger. Generally, the sensitivities decrease with an increase in the Young's moduli. This trend levels off for higher Young's moduli. As the stiffness of the pipe increases to very high values in comparison to the filler it completely dominates the deformation in the cement to the point where small changes in E_1 have little effect. At the reference state, the sensitivities are approximately 2.56 kPa GPa⁻¹ (E_1) and 1.2 MPa GPa⁻¹ (E_2). Both sensitivities are positive, i.e. an increase in any Young's modulus causes an increase in stresses.

Table B.1: Material properties of the specific heat exchangers and the storage material used in IGLU project

Materials	Density $ ho_{\rm SR}$ / kg m ⁻³	Thermal Conductivity $\lambda_{\rm TS}$ / W m ⁻¹ K ⁻¹	Thermal Expansion $\alpha_{\rm TS}$ / ${\rm K}^{-1} \cdot 10^{-6}$	Heat Capacity $c_{\rm TS}$ / J kg $^{-1}$ K $^{-1}$	Elastic Modulus E / GPa
Heat exchanger Alu-PE composite	1825	0.4	30	2200	68.9
Storage material Füllbinder L	1583	0.96	10.7	2083	1.9

The effect of the Poisson's ratio on the peak stress is sublinearly increasing, and the one of the storage material again has a stronger influence than that of the heat exchanger, see Fig. B.4c and Fig. B.4d. The

22 sensitivity with respect to the Poisson's ratio is higher than the one with respect to changes in the Young's

moduli. At the reference state, the sensitivities are approximately 0.04 MPa (ν_1) and -1.53 MPa (ν_2). In

² particular $\mathcal{D}_{\nu_1} > 0$ and $\mathcal{D}_{\nu_2} < 0$ highlight the qualitatively opposite impact of both parameters. Increasing



Figure B.4: Sensitivity of the objective tensile stress with respect to the material parameters. (a)/(b): Young's modulus of the heat exchanger/the storage material; (c)/(d): Poisson's ratio of the heat exchanger/the storage material.

³ the Poisson's ratio of the storage material can have a significant reducing effect on the peak stress.

The influence of the geometrical configuration of the heat exchanger is more polymorph. The sensitivity of the inner diameter is positive and exhibits a comparatively dominant influence in the region where the thickness of the heat exchanger is high, while the outer diameter has negative sensitivity when the thickness is extremely low. As the thickness increases, the sensitivity is positive and eshibits a peak value. In the reference state, the sensitivities are approximately 0.014 MPa mm⁻¹ (r_0) and 0.003 MPa mm⁻¹ (r_1). Under standard conditions, the sensitivities of r_0 and r_1 have approximately the same order of magnitude as one of S with respect to the peak stress.

The first-order partial derivative of the peak stress with respect to the tube pitch in Fig. B.5c shows the existence of a threshold value above which the sensitivity is practically zero, i.e., a further increase in tube pitch has no impact. At the reference state, the sensitivity is -0.005 MPa mm⁻¹, i.e. increasing the tube pitch will lower the peak tensile stress.

So far, the effect of each parameter was studied in isolation. In practical applications, an independent choice may not always be possible. In the subsequent sections, the dimensionless solution is used to study



Figure B.5: Sensitivity of the objective tensile stress with respect to the geometrical parameters, (a)/(b) the inner/outer radius of the heat exchanger, (c) the tube pitch.

5 the effect of multiple parameters at once.

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- \rightarrow Analytical solution in the near field of the heat exchanger for extensive sensitivity analyses.
- \rightarrow Optimisation of thermal energy stores from a thermo-mechanical perspective.
- \rightarrow Case studies for typical heat exchanger materials and geometries.
- \rightarrow Analysis of water-saturated cement heat store.

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